

Download Control Design And Analysis For Underactuated Robotic Systems

viii Preface analysis presented in a systematic way for 14 underactuated robotic systems including those with multiple-degree-of-freedom and/or with underactuation degree two. The last two decades have witnessed considerable progress in the study of underactuated robotic systems (URSs). Control Design and Analysis for Underactuated Robotic Systems presents a unified treatment of control design and analysis for a class of URSs, which include systems with multiple-degree-of-freedom and/or with underactuation degree two. Contents 3.3 Swing-up Controller 48 3.4 Global Motion Analysis 51 3.4.1 Convergence of Energy 52 3.4.2 Closed-Loop Equilibrium Points 56 3.5 Discussion 64 Lesen Sie „Control Design and Analysis for Underactuated Robotic Systems“ von Xin Xin erhältlich bei Rakuten Kobo. Registrieren Sie sich noch heute und sichern Sie sich \$5 Rabatt auf Ihren ersten Kauf. The last two decades have witnessed considerable progress in the study of underactuated robotic systems - Control Design And Analysis For Underactuated Robotic Systems